

# Entanglement Filtering in 3D Tensor-Network Renormalization Group

*XL* and Kawashima, arXiv:2311.05891

*XL* and Kawashima, arXiv:2412.13758

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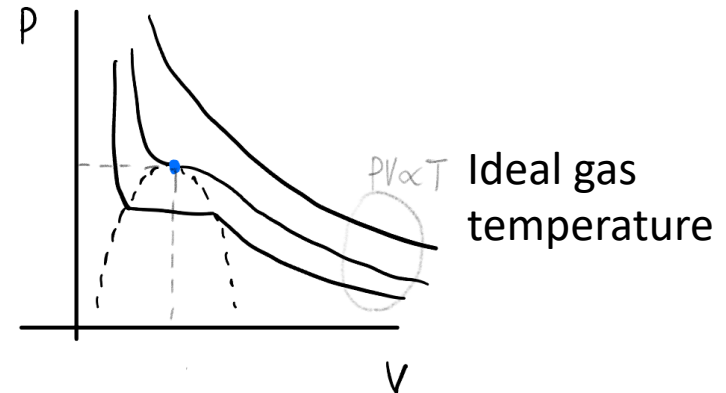


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# Universality, Criticality, and RG



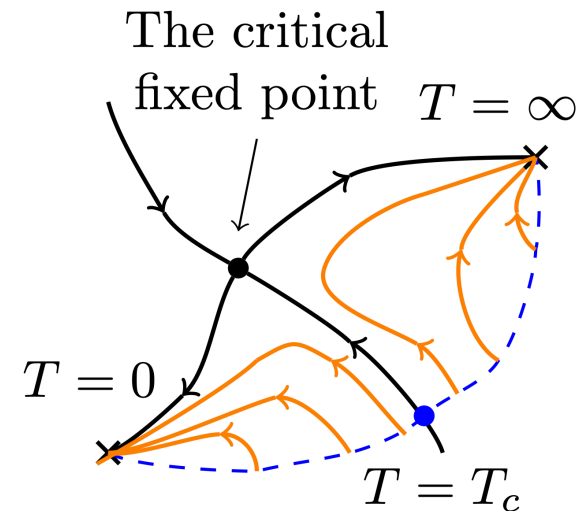
$G$   
Einstein's GR



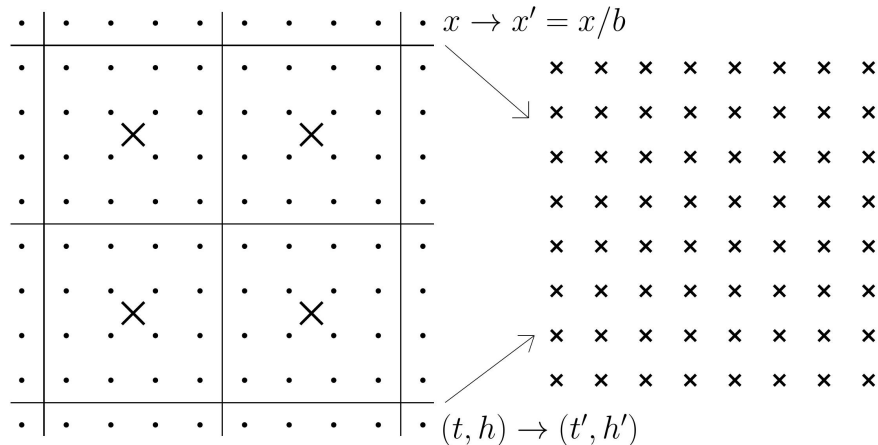
When liquid-gas transition kicks in,  $P_c, V_c$  depends on gas molecules.  
 $(P - P_c) \propto (T - T_c)^\delta \rightarrow$  **Critical exponents** are universal

Due to interaction, theoretically predicting  $\delta$  is challenging.

In 1960s and 70s, people like Kadanoff, Wilson, Fisher developed an idea called renormalization group (RG) to calculate these exponents.



# Block-spin: prototype of real-space RG



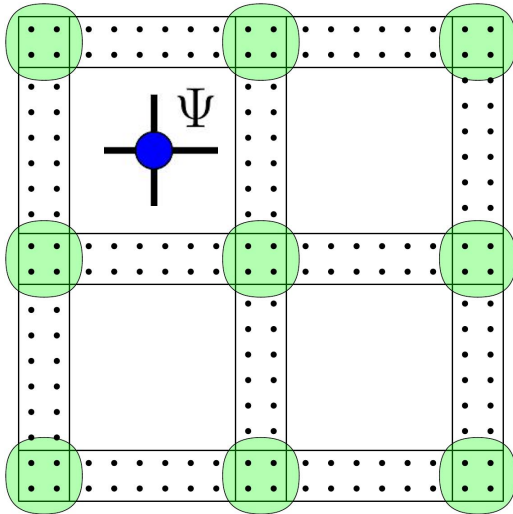
Wilson (1975) implemented a numerical 3x3 block-spin map by keeping 217 couplings of 2D Ising:

- High accuracy—1% or even 0.1% for first two exponents
- “Difficult for 3D Ising... since 3x3x3 block contains about 30 spins, corresponding to  $10^9$  configurations”

Migdal-Kadanoff bond moving (1976) gives  $x_\epsilon = 2.1$  (best-known value is 1.41) for 3D Ising; the relative error is about 50%...

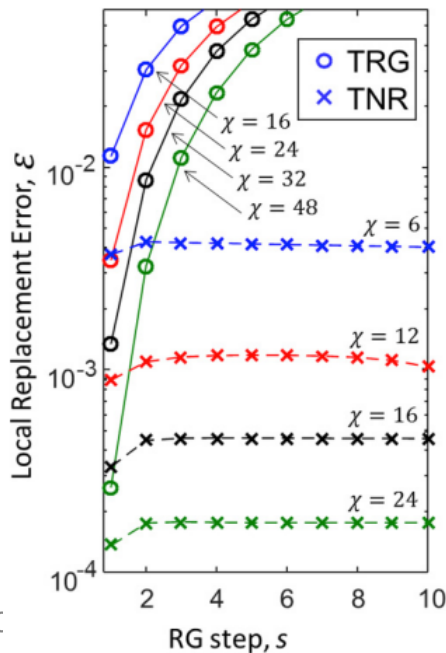
- Uncontrolled approximation
- One-shot approximation

# Tensor-network reformulation



2D classical  $\rightarrow$  1D quantum chain (radial quantization)  
 $\rightarrow$  Entanglement-entropy area law:  $S(L) \sim S_0$  [due to Levin and Nave, *PRL* **99**, 120601 (2007)]

Constant  $S_0$  can justify the practice of keeping constant number of couplings!



Systematically improvable 2D real-space RG!

exact	TNR(6)	TNR(16)	TNR(24)
0.125	0.125679	0.124941	0.124997
1	1.001499	1.000071	1.000009
1.125	1.125552	1.125011	1.124991
1.125	1.127024	1.125201	1.125027
max err.	0.83%	0.046%	0.0069%

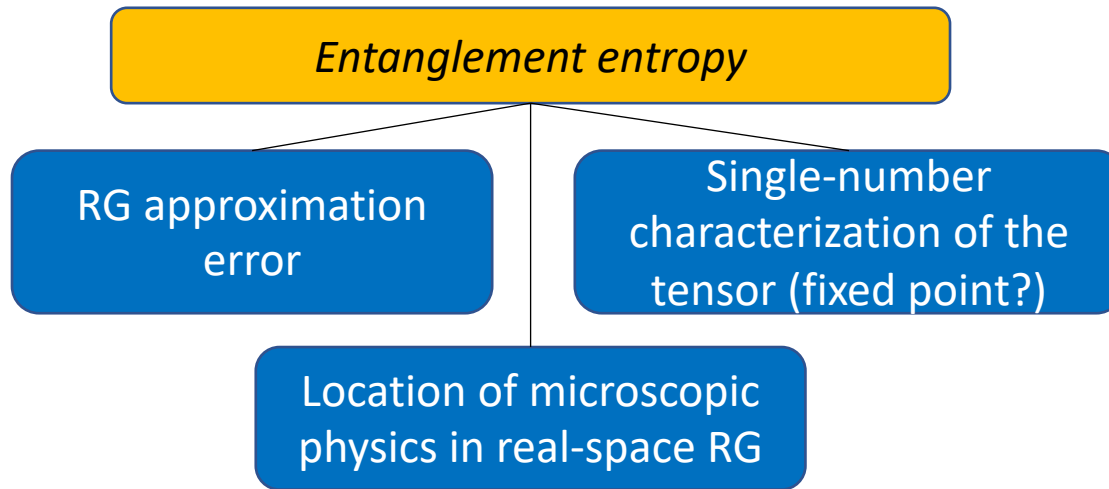
Evenbly and Vidal, *PRL* **115**, 180405 (2015)

# EE and Tensor-Network RG

Real-space RG methods often *work better in low dimensions*, but *struggle more in higher dimensions*:

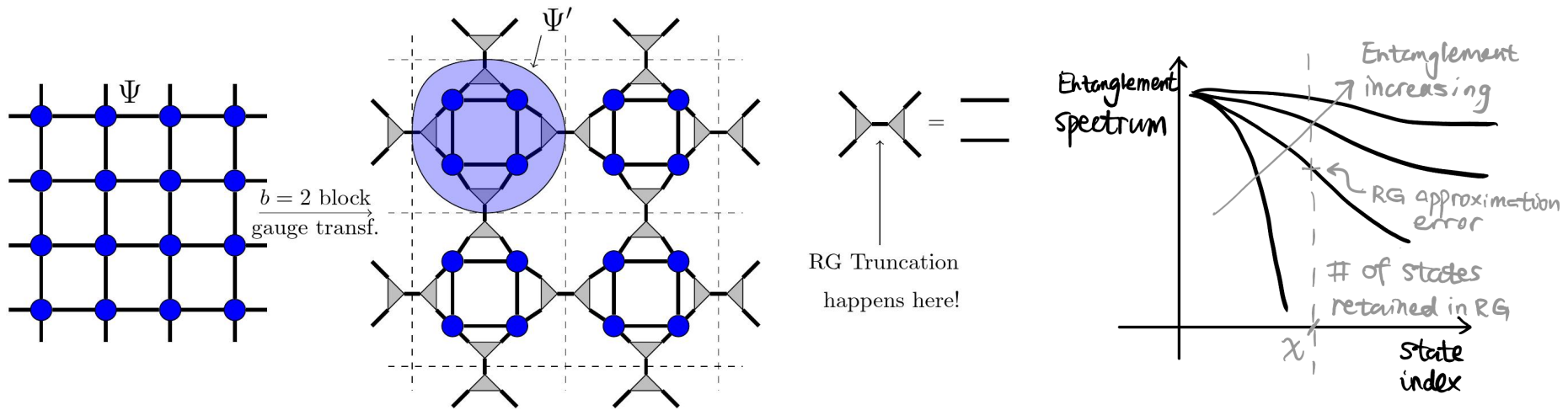
- Migdal-Kadanoff bond moving can be intuitively seen as a perturbative approach starting from  $d_L$
- Computationally, dimensionality of coupling constant space grows faster

For Tensor-Network RG, entanglement entropy is a tool for understanding



# EE and TNRG: block-tensor map

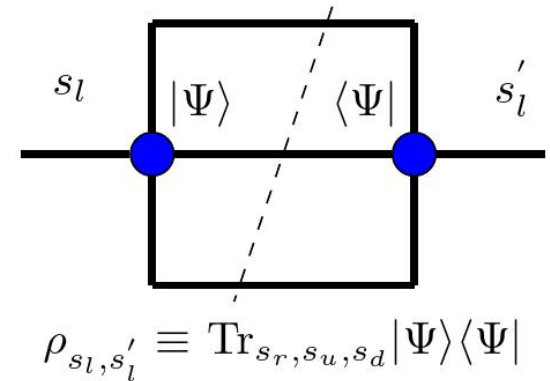
Block idea in tensor-network language: *block-tensor transformation*



An RG flow in tensor space:  $\Psi^{(0)} \rightarrow \Psi^{(1)} \rightarrow \Psi^{(2)} \rightarrow \dots$

Takeaways:

- Entanglement entropy  $\nearrow$  indicates RG error  $\nearrow$
- Changing entanglement entropy indicates your tensor isn't fixed (but we *wish* to have a fixed-point tensor).



# EE and TNRG: block-tensor in 3D

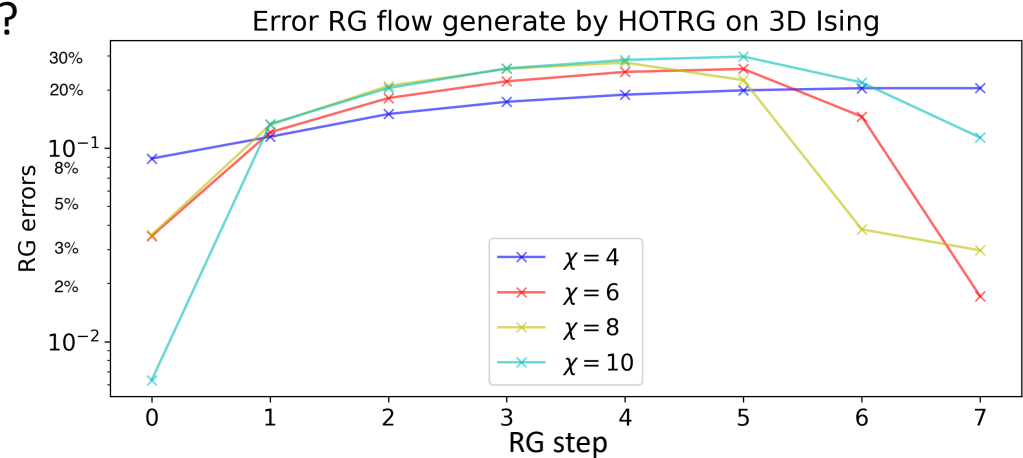
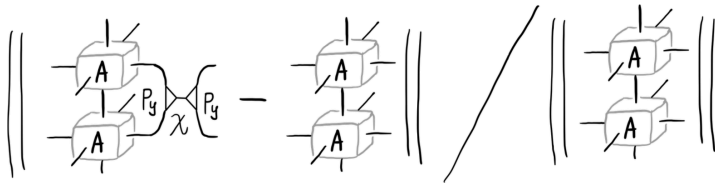
UV physics      Universal physics

$$S(L) = \alpha L - F$$

Linear growth of  $S$  marks a *qualitative* difference between 3D and 2D for block-tensor RG!

Consequences on the numerical side?

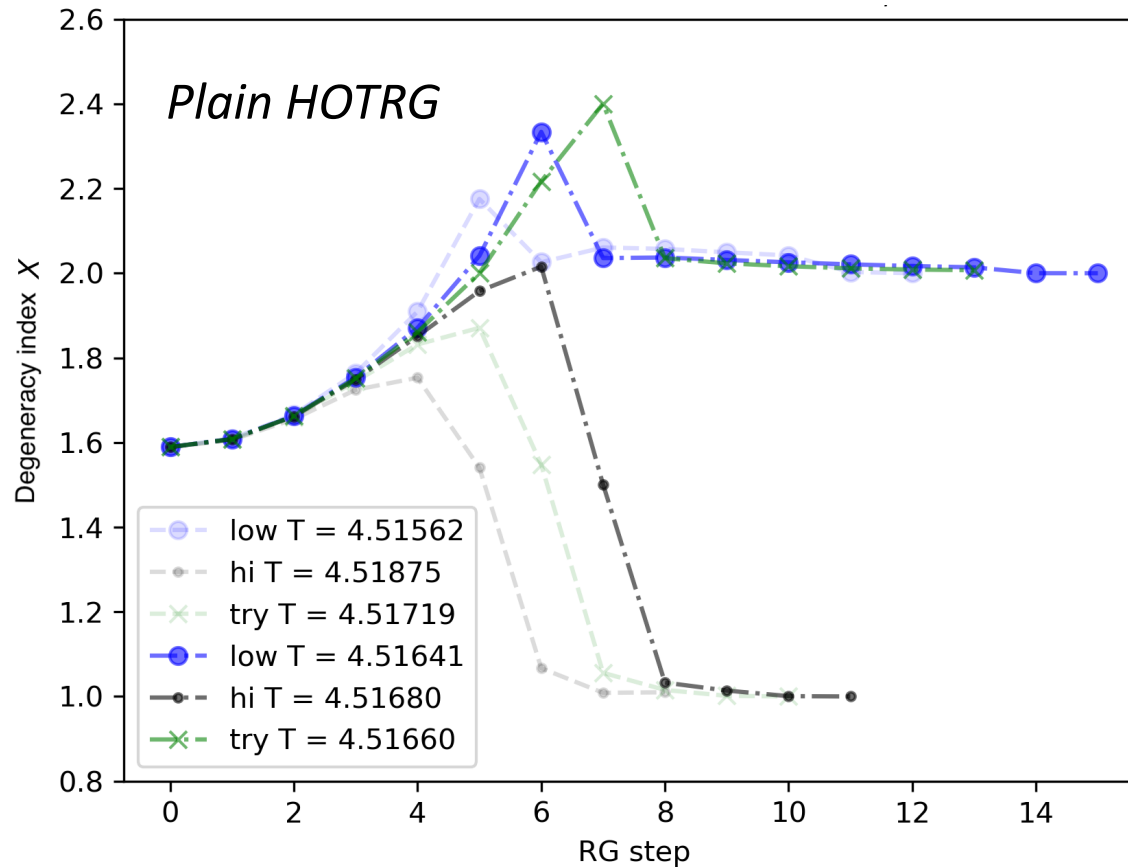
- Large RG truncation errors
- Increase states doesn't help



# Block-tensor transformation in 3D

We perform a thorough analysis for bond dimensions up to 20

Estimates fail to convergence w.r.t RG step!

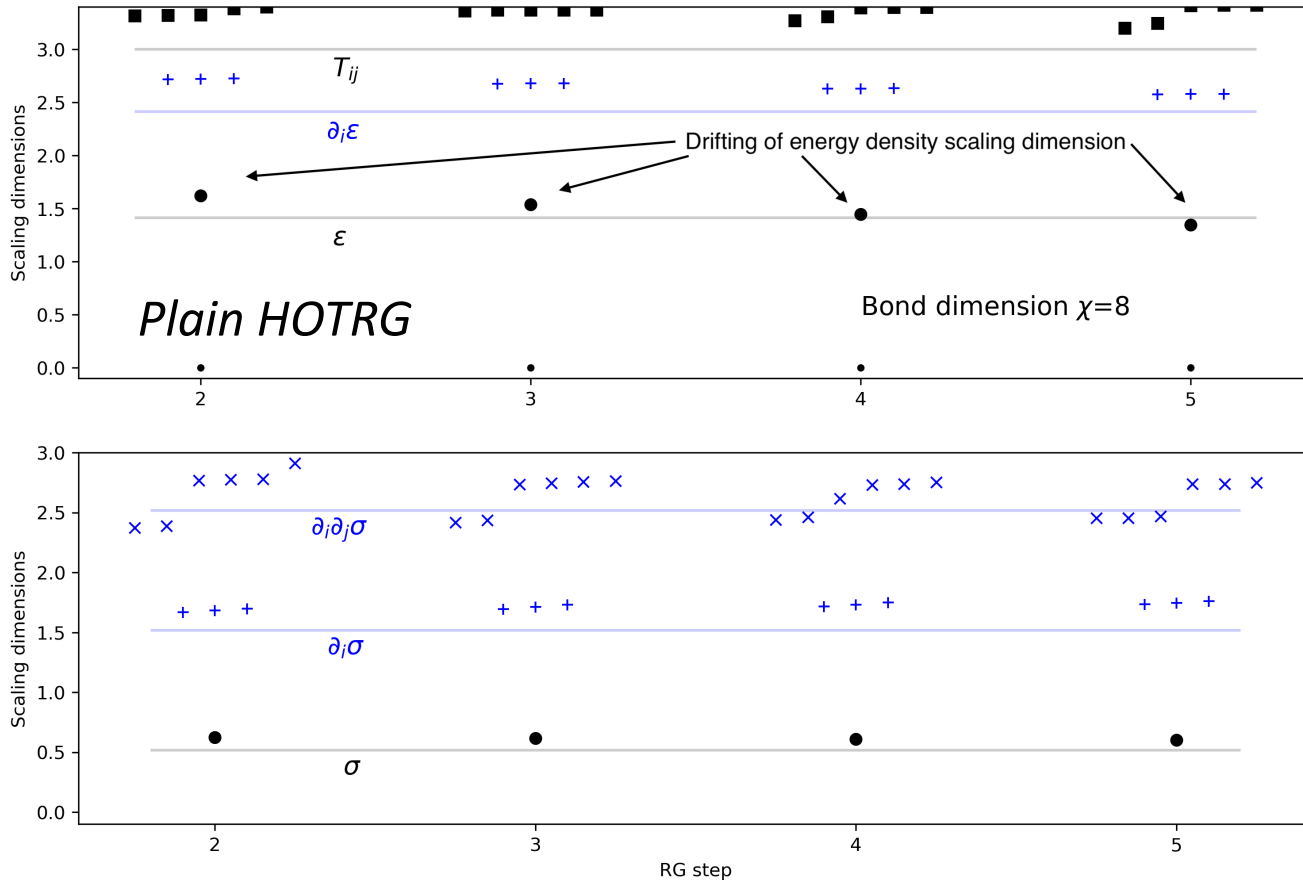




# Block-tensor transformation in 3D

We perform a thorough analysis for bond dimensions up to 20

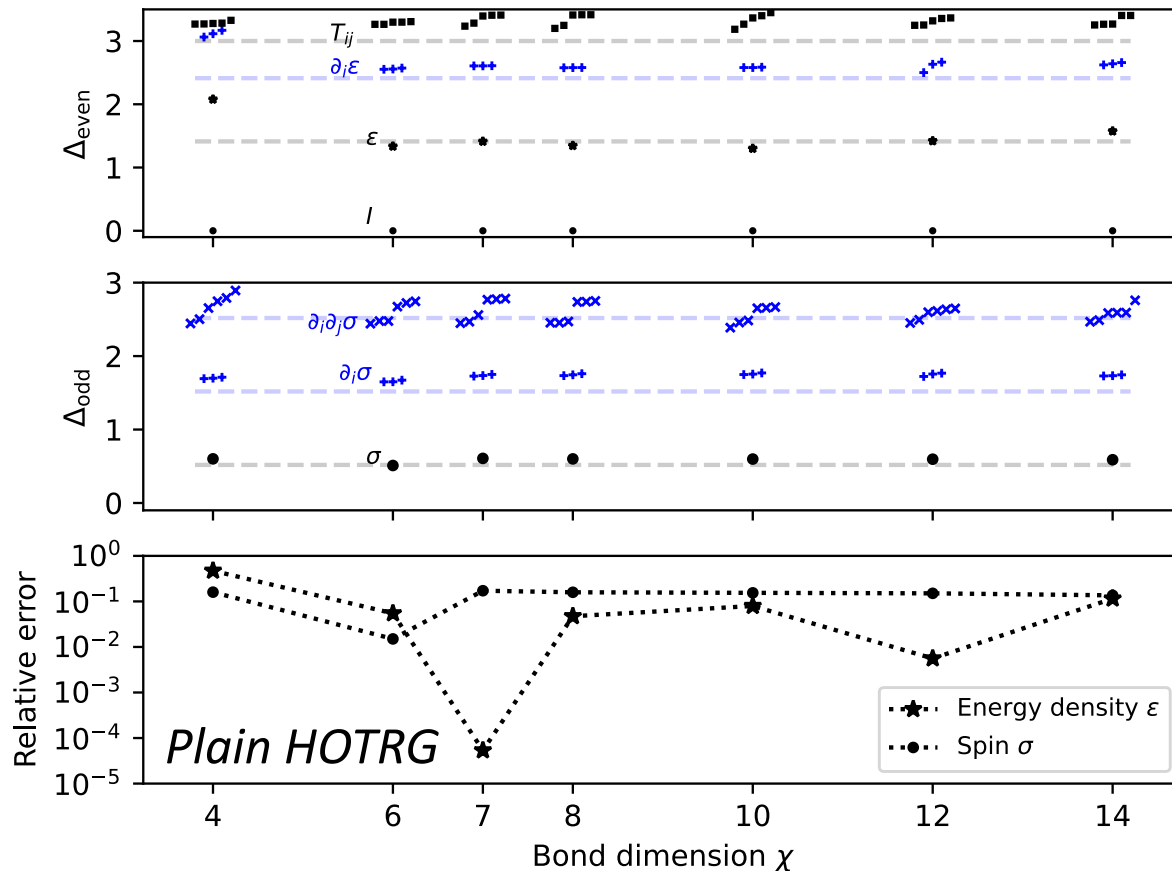
## Estimates fail to convergence w.r.t RG step!



# Block-tensor transformation in 3D

- Estimated **scaling dimensions**  $\Delta$  versus the **bond dimension**  $\chi$

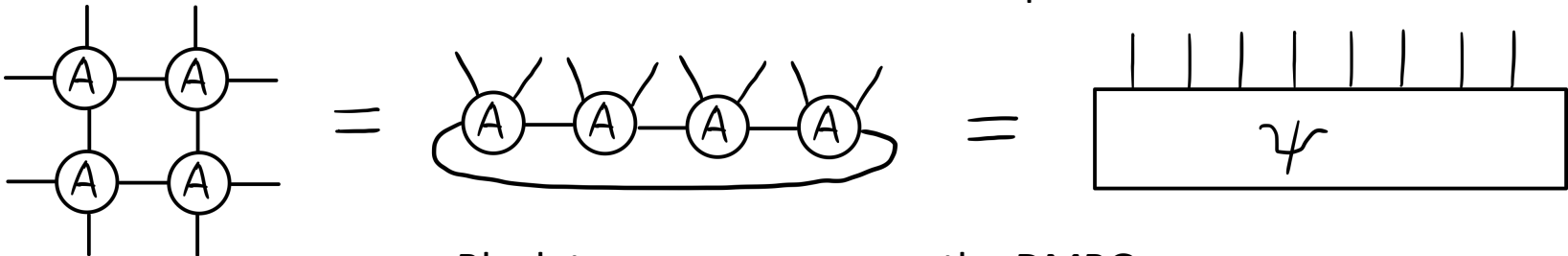
(Choose the estimates that are closest to the known value)



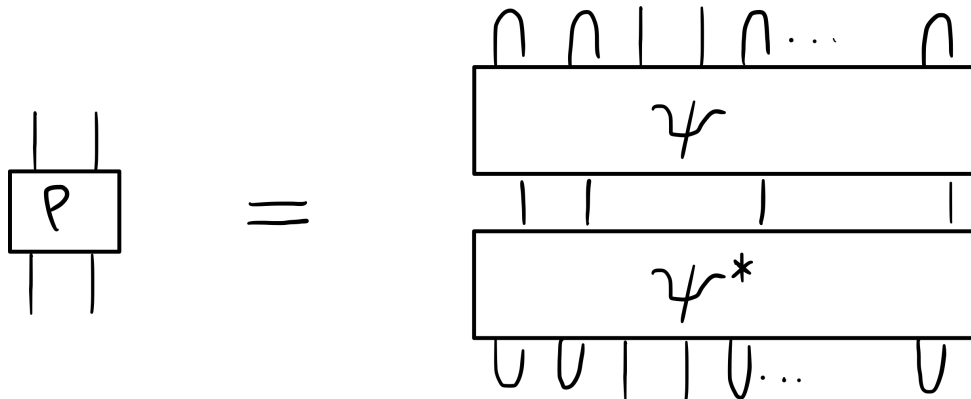
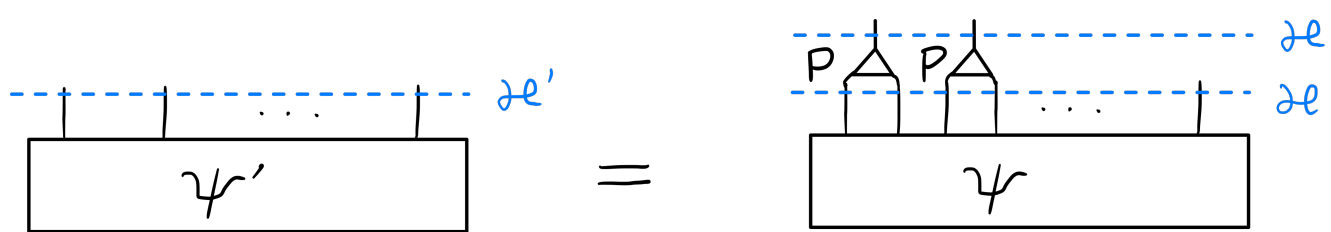
# Entanglement filtering: basic idea

Area law can be circumvented in coarse-grained description if the boundary of the block is "dissolved"

Invoke the wave function interpretation

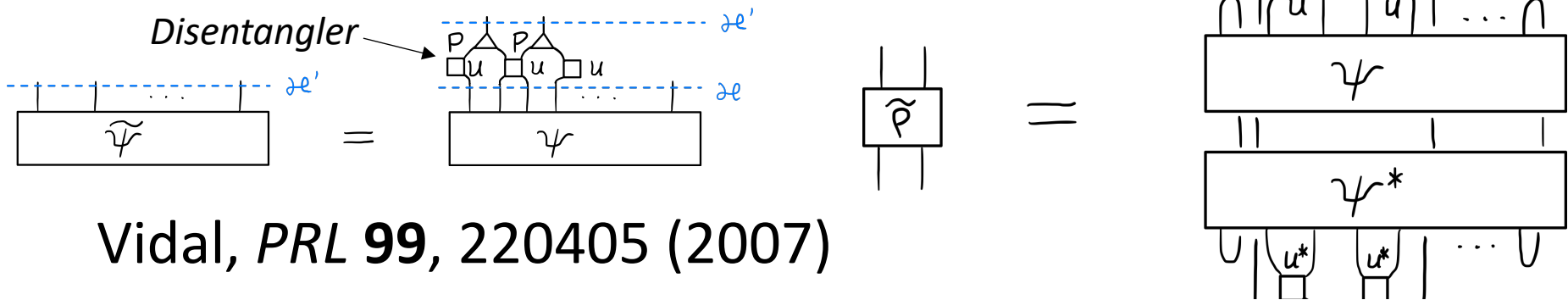


Block-tensor map seen as the DMRG

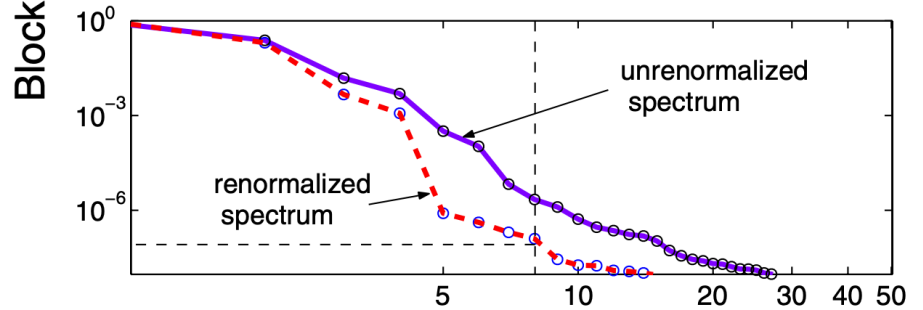
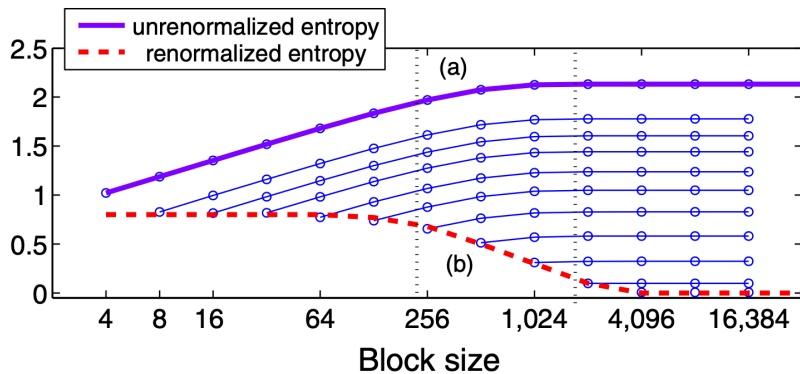
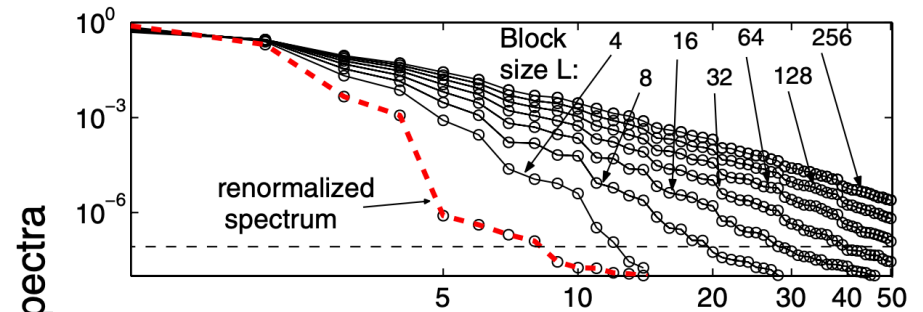
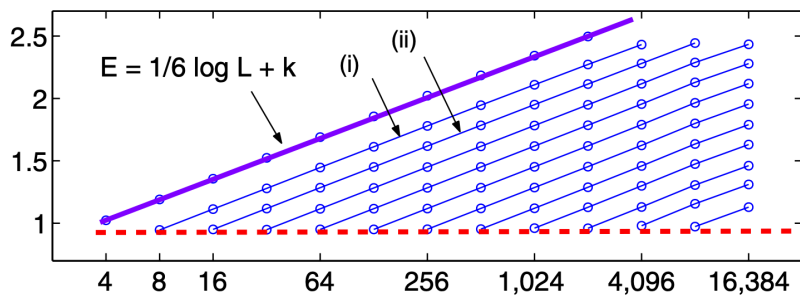


# Entanglement filtering: basic idea

Area law can be circumvented in coarse-grained description if the boundary of the block is "dissolved"

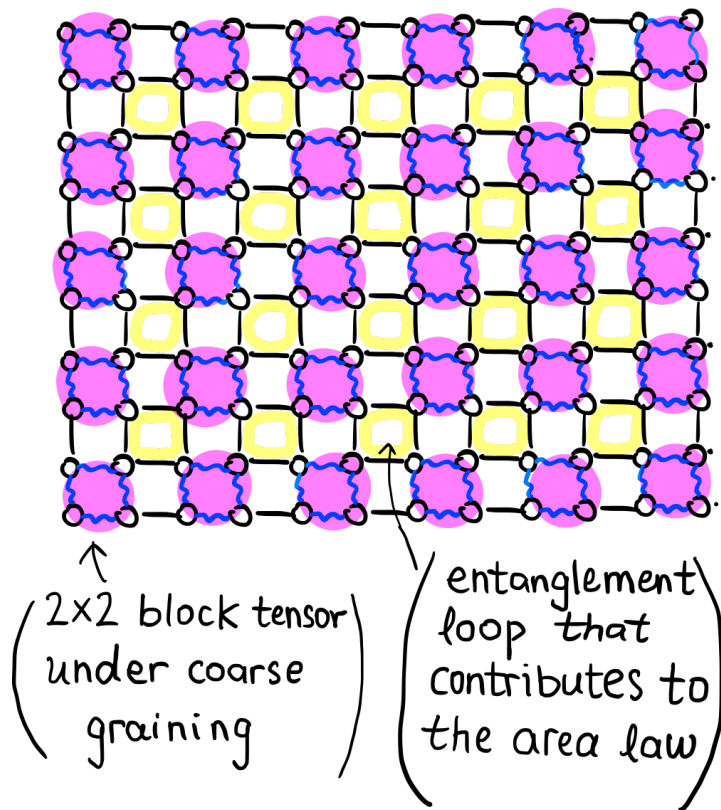


Vidal, *PRL* **99**, 220405 (2007)

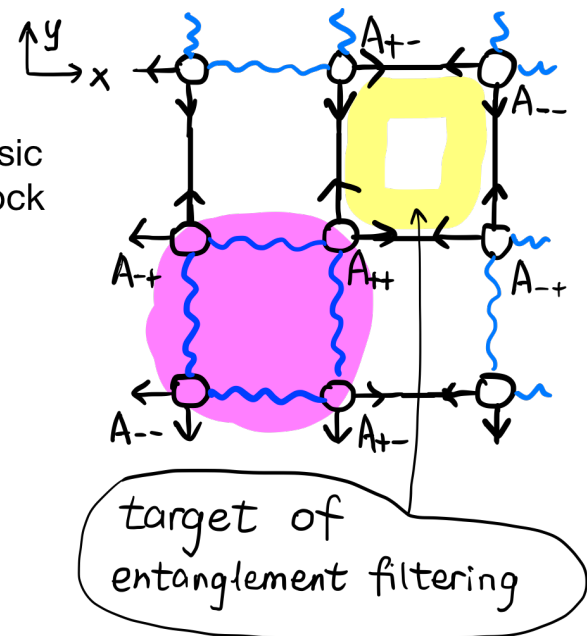


# Proposed filtering scheme

Demonstrated in the 2D square lattice, here is how to *integrate Entanglement Filtering into a block-tensor transformation*:



with the basic building block patch as



# Proposed filtering scheme

We adopt the graph-independence idea in GILT

+

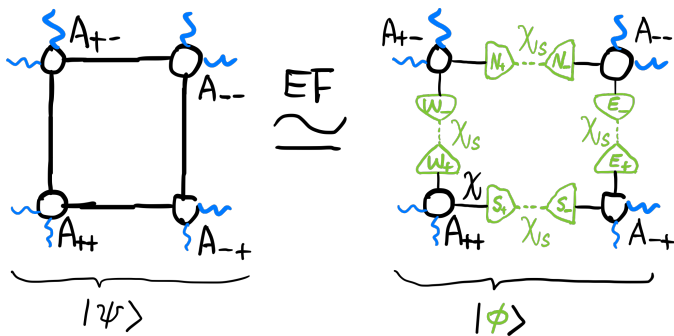
Use another way to find the filtering matrix: full environment truncation

Demonstrated in the 2D square lattice, we propose:

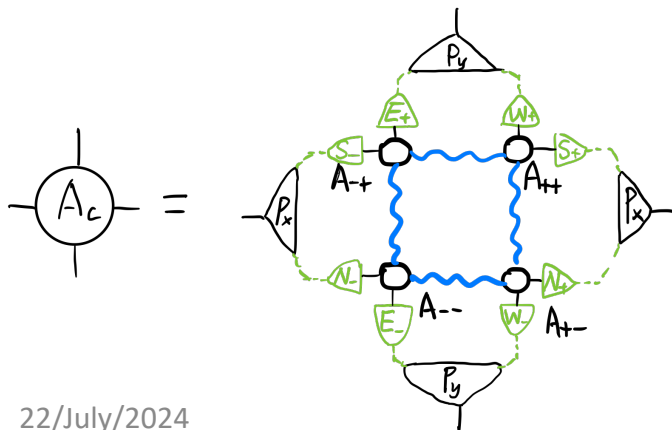
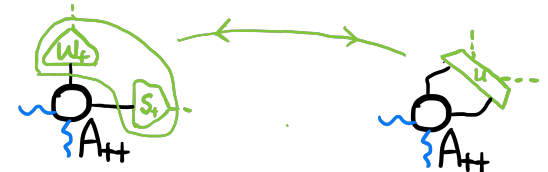
Hauru, Delcamp, and Mizera, *PRB* **97**, 045111 (2018)

Evenbly, *PRB* **98**, 085155 (2018)

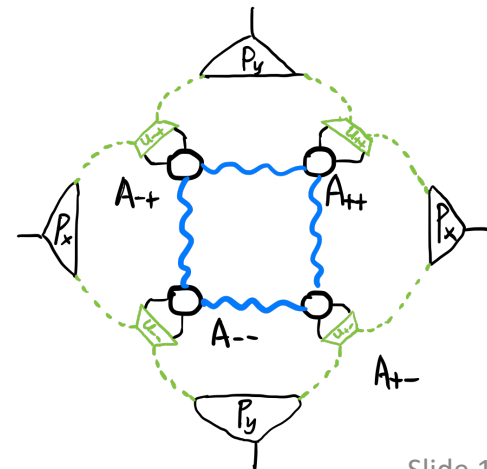
***XL and Kawashima***, arXiv:2412.13758



Disentangler interpretation:



Disentangler interpretation:



# Entanglement filtering in 3D

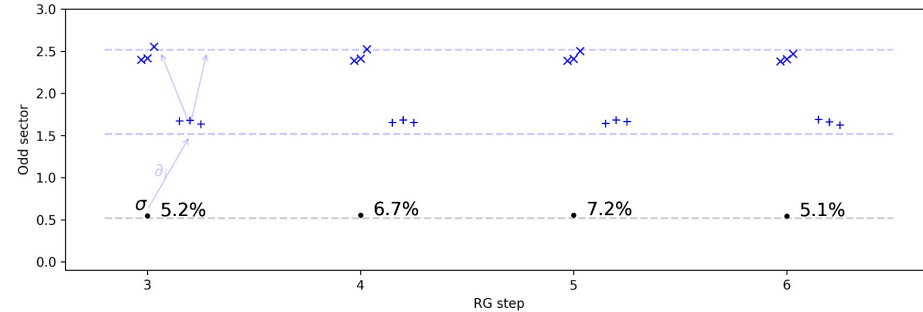
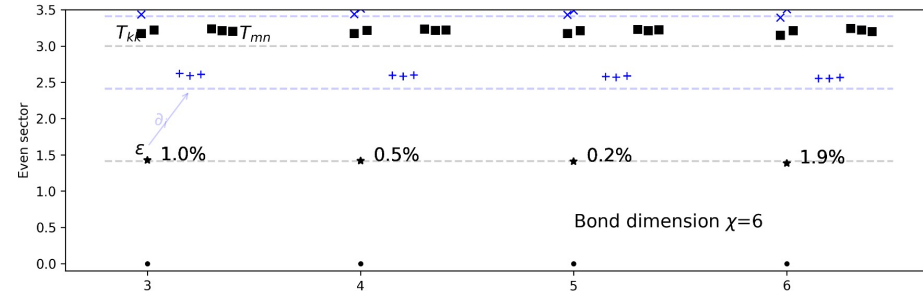
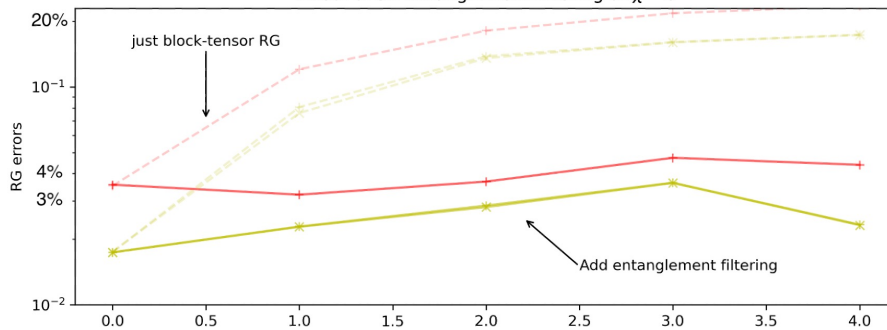
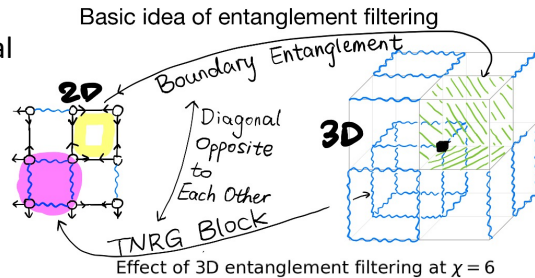
Entanglement entropy grows in 3D:

$$S = \alpha L - F$$

Fixed # of couplings:

*Filtering out the boundary entanglement is essential in 3D!*

2D filtering:  
Evenly and Vidal  
Hauru *et al.*



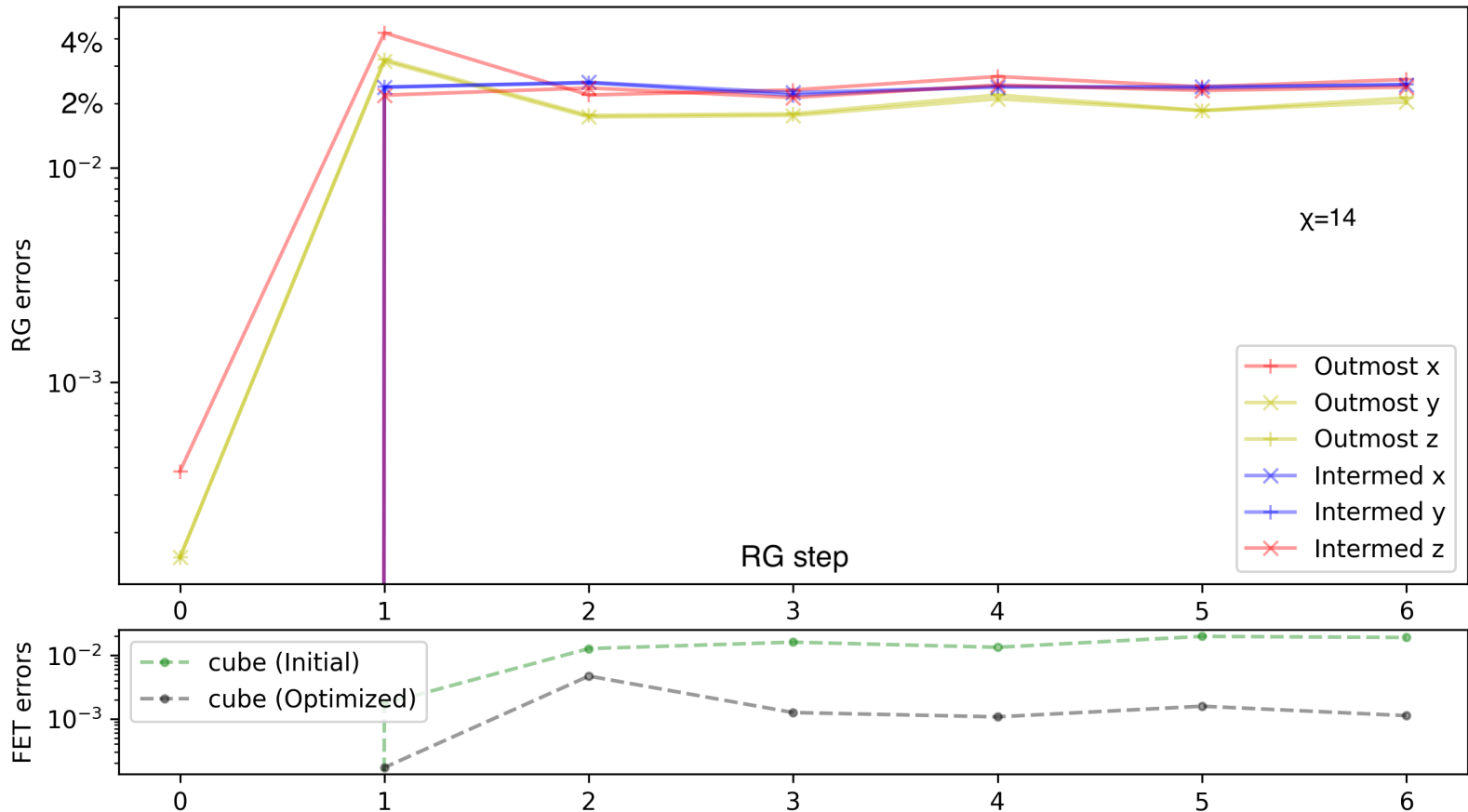
Note: the accuracy of exponents  $\chi_\epsilon, \chi_\sigma$  ranges from 1% to 0.01% for the majority of well-developed methods

***XL and Kawashima, arXiv:2412.13758***

# Entanglement filtering in 3D

RG truncation errors versus the bond dimension  $\chi$

$\chi$	6	8	11	14
RG error	6%	7%	4%	2%



***XL and Kawashima, arXiv:2412.13758***



# Entanglement filtering in 3D

Scaling dimensions versus the bond dimension  $\chi$

$\chi$	6	8	11	14
min error	5%	4%	3%	0.4%
max error	8%	6%	6%	0.5%

$\chi$	6	8	11	14
min error	0.1%	4%	1%	2%
max error	1%	5%	6%	4%

Table 8.1: Estimation errors for  $x_\sigma$  versus bond dimension

Table 8.2: Estimation errors for  $x_\epsilon$  versus bond dimension

For spin field  $x_\sigma$

- ✓ Mild decay of error with increasing bond dimension
- ✓ The magic bond dimension is  $\chi = 14$

For energy density field  $x_\epsilon$

- ✓ Decay of error isn't clear; but there is no apparent increase either.
- ✓ The magic bond dimension is  $\chi = 6$

*Remark: in 2D TNR, the systematical improvement is demonstrated by increasing the bond dimension  $\chi = 6 \rightarrow 16 \rightarrow 24$*

# Summary

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- The Kadanoff's block idea has been upgraded to become a *reliable* 3D real space RG
- In its best scenario, the error of  $x_\sigma$  is 0.4% and that of  $x_\epsilon$  is 0.1%  
 $x_\sigma, x_\epsilon$   $m \sim (\lambda - \lambda_c)^\beta$

TN Methods	Proposed	HOTRG	2D MERA	iPEPS
Smallest error	0.1%, 0.4%	0.9%	1.0%	1.7%
Computational cost	$\chi^{12.5}$	$\chi^{11}$	$\chi^{16}$	$D^{10\sim 14}$

- The *conformal tower structure* is unique among all well-established numerical techniques
- It is a solid step towards a systematically improvable numerical RG